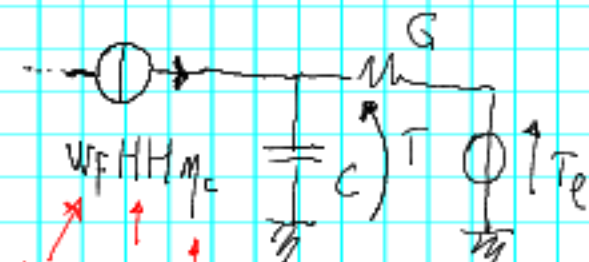


22/06/2016

1

E1] 10/09/2014, E2

a)



$$\frac{W_F}{s} \quad \frac{H}{kg} \quad \frac{H}{kg} \quad \frac{\eta_c}{\#}$$

$$\rightarrow \frac{H}{s} = 17W$$

$$HH = 50 \text{ kJ/kg}$$

$$\eta_c = 0.8$$

$$G = 30 \text{ W/}^\circ\text{C}$$

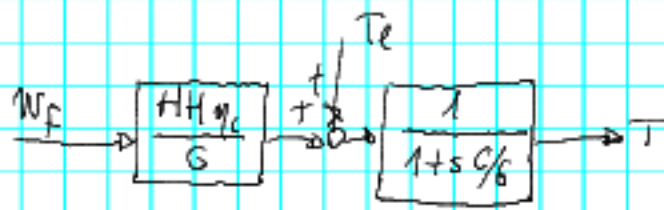
$$C = 12 \text{ kJ/}^\circ\text{C}$$

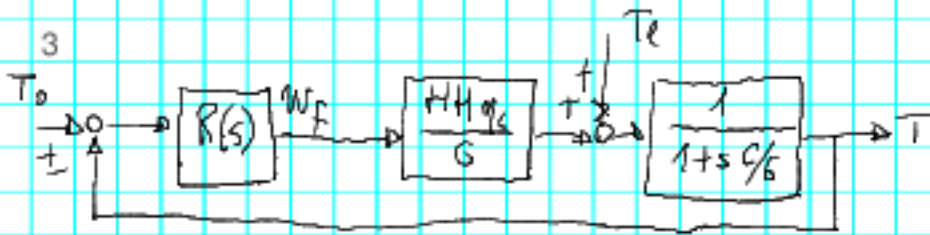
$$b) \quad c \dot{T} = HH\eta_c w_f - G(T - T_e)$$

STATE  
INPUTS  
PARAMETERS

$$(sC + G)T = HH\eta_c w_f + GT_e$$

$$\left(1 + s \frac{C}{G}\right)T = \frac{HH\eta_c}{G} w_f + T_e$$





Natural choice: PI tuned by cancellation

$$P(s) := \frac{T(s)}{w_F(s)} = \frac{HH\omega_c/G}{1+sC/G}, \quad L(s) = R(s)P(s)$$

$$\text{I want } L(s) = \frac{\omega_c}{s} \Rightarrow R(s) = \frac{\omega_c}{s} \frac{1+sC/G}{HH\omega_c/G}$$

in the adiabatic case

$$\text{settling time } 5 \text{ min} \Rightarrow \omega_c = \frac{1}{t_{\text{set}}/5} = \frac{1}{60} \text{ r/s}$$

$$\Rightarrow R(s) = \frac{1/60}{s} = \frac{1+s \cdot 12 \cdot 10^3/30}{5 \cdot 10^7 \cdot 0.8/30} = \frac{1+400s}{8 \cdot 10^8 s}$$

$$C = 12 \text{ KJ/}^\circ\text{C} = 12000 \text{ J/}^\circ\text{C}$$

$$G = 30 \text{ W/}^\circ\text{C}$$

$$HH = 50 \text{ W/Kp} = 5 \cdot 10^7 \text{ J/Kg}$$

$$|H| = H H_m \cdot \alpha$$

$$H_c = H_{cr} \cdot \beta$$

" $H_m$ " stands for "mass"

$$\beta \approx 1$$

$$L(s) = \frac{\omega_c}{s} \cdot \frac{H_m \alpha}{H_m \beta} \cdot \frac{1}{s} = \frac{\omega_c \alpha}{s^2}$$

$R$ , reset, or  
integral values

$P$ , functioning  
with real values

⇒ decreasing  $H_m$  and/or  $H_c$  decreases response speed

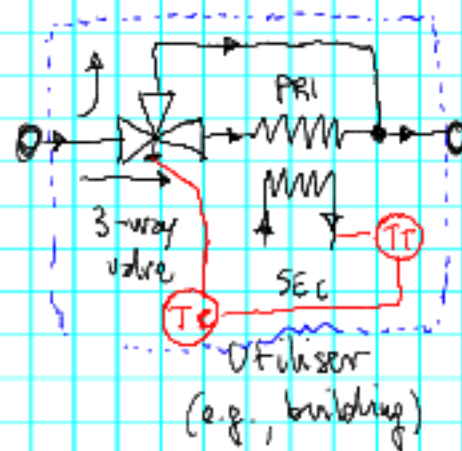
⇒ the time affects multiply

⇒ i.e.  $H_m$  and/or  $H_c$  decrease,  $\omega_p$  increases

# • Control of simple heat networks (just 2 flow nodes)

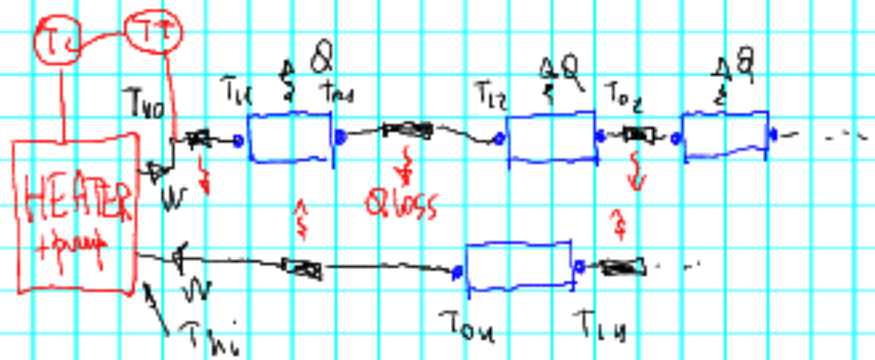
Two basic topologies (simplified)

①



plus some logic to bypass if no secondary flow

7



### PROS

- min piping length
- $\Rightarrow$  min  $Q_{loss}$

### CONS

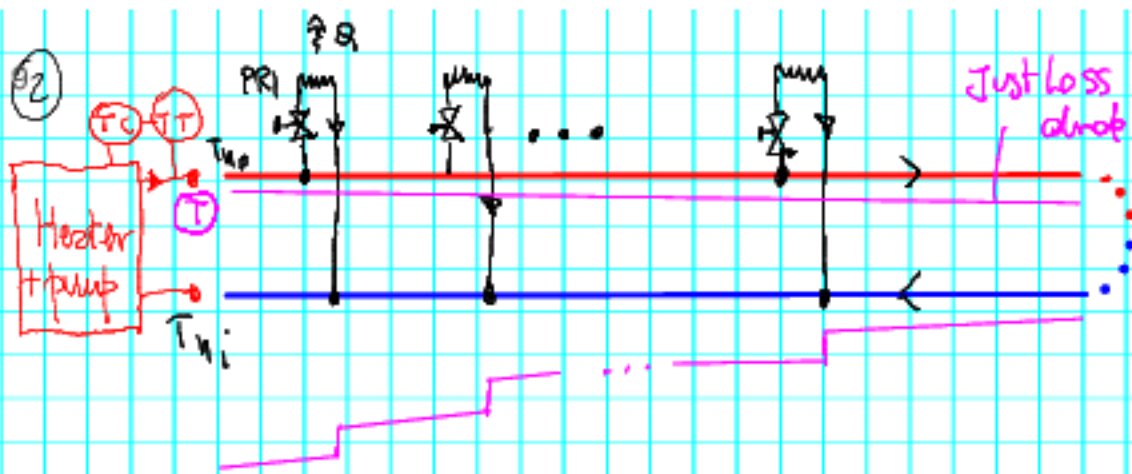
- Each utiliser disturbs those downstream
- $\Rightarrow$  some central control useful

Requirement : control  $T_{ho}$  so that  $T_{o1}$  is high enough  
For the last user to get heat

8 Typically are principles HLGH flow rates in the ring and low difference between the  $\Delta P$  in  $\Rightarrow$  pumping power may be significant

Advisable for small installations, like a compound of residential buildings.





Cons: in general  
more piping

Pros: no disturbance for  
downstream users in  
the hot pipe

No need for centralized control

objectives for the central heater: keep the heating  $T_{hi}$  as  $\rightarrow$  disturbance  
ADVISABLE for large networks

□