



# AUTOMATION OF ENERGY SYSTEMS

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Reg. No. \_\_\_\_\_

Last name \_\_\_\_\_

Given name(s) \_\_\_\_\_

Signature \_\_\_\_\_

- Answer the questions in the spaces provided.
- If you run out of room for an answer, continue on the back of the page.
- Hand in *only* this booklet. No additional sheets will be accepted.
- Scoring also depends on clarity and order.

1. Consider an islanded electric generator, and let the transfer function from the command  $\theta$ , in the range 0–1, to the normalised variation  $\delta P_g$  of the generated power, be

$$g(s) = \frac{320}{1 + 15s}.$$

- (a) Draw the block diagram representing the generator connected to a local network, assuming an equivalent time constant  $T_A$  of 10 s.

- (b) Tune a power/frequency controller in the form of a real PID for a phase margin of  $50^\circ$  and a closed-loop dominant time constant of  $5\text{ s}$ .

- (c) Express the transfer function from the electric power demand variation  $\Delta P_e$  to the normalised frequency error  $\delta\omega$ .

2. Consider a thermal system in which a body of capacity  $C = 20 \text{ kJ/}^\circ\text{C}$  is heated by a combustor. The fuel calorific power is  $HH = 48 \text{ MJ/kg}$ , and the combustion efficiency  $\eta_c$  varies from a minimum of 0.6 to a maximum of 0.8. The body disperses heat through a thermal conductance  $G = 70 \text{ W/}^\circ\text{C}$ , to a prescribed external temperature  $T_e$ , and is subject to a disturbance radiative power  $P_r$ .
- (a) Draw an electric equivalent of the system.

- (b) Determine a linear regulator acting on the fuel flow rate  $w_f$  [kg/s] to control the body temperature  $T$ , reasoning on the worst-case situation, so that the settling time of the response of the controlled temperature to a set point step variation does not exceed 10 *min*.

- (c) Estimate (even roughly) the same settling time in the best-case situation.

3. Describe the “boiler follows”, policy for the control of thermoelectric generators, highlighting and briefly justifying its major advantages and disadvantages.

4. Illustrate the “time division output” actuation scheme, indicating the main reasons that make its application advisable, and commenting on how its base period has to be chosen.